

Surface Integral & Stokes theorem

- surfaces
- surface area

We are familiar with curves in the plane. The study of surfaces in the space \mathbb{R}^3 is somehow parallel to it.

First, parametric surfaces.

A parametric surface is a continuous map from some set $E \subset \mathbb{R}^2$ to \mathbb{R}^3 . The set E is quite flexible, usually it is an open set or assume the form $[a, b] \times [c, d]$. Thus write

$$\vec{r}: E \rightarrow \mathbb{R}^3, \quad \vec{r}(u, v) = (x(u, v), y(u, v), z(u, v)) \quad \text{or} \\ = x(u, v) \hat{i} + y(u, v) \hat{j} + z(u, v) \hat{k}.$$

.It is regular if the vectors

$$\frac{\partial \vec{r}}{\partial u} = (x_u, y_u, z_u) \quad \text{and}$$

$$\frac{\partial \vec{r}}{\partial v} = (x_v, y_v, z_v)$$

are linearly independent at every $(u, v) \in E$. Recall that two 3-vectors \vec{a}, \vec{b} are linearly independent iff $\vec{a} \times \vec{b} \neq (0, 0, 0)$.

A parametric surface is regular if x, y, z are C^1 -functions of u, v and

$$\frac{\partial \vec{r}}{\partial u} \times \frac{\partial \vec{r}}{\partial v} \neq (0, 0, 0), \quad \text{or}$$

$$\left| \frac{\partial \vec{r}}{\partial u} \times \frac{\partial \vec{r}}{\partial v} \right| > 0 \quad \text{on } E.$$

There are 3 ways to define a (geometric) surface in \mathbb{R}^3 .
The first one is to use parametric surfaces.

A set S in \mathbb{R}^3 is called a regular surface if there is a regular parametric surface $\vec{r}: E \rightarrow \mathbb{R}^3$ such that it maps E 1-1 onto S .

The second approach is the explicit surfaces. Let $f(x, y)$ be a C^1 -function over some $(x, y) \in G$, G open set in \mathbb{R}^2 . Then the set

$$\{(x, y, f(x, y)) : (x, y) \in G\}$$

forms an explicit surface. In fact, $(x, y) \mapsto (x, y, f(x, y))$ can be viewed as a parametrization. We have

$$\frac{\partial \vec{r}}{\partial x} = (1, 0, f_x), \quad \frac{\partial \vec{r}}{\partial y} = (0, 1, f_y)$$

which is clearly linearly independent. Similar situation applies to

$$(x, g(x, z), z), \quad \text{and} \quad (h(y, z), y, z).$$

The third approach is the implicit surfaces. Very often, a surface is given by the level set of some f on \mathbb{R}^3 . Consider the set

$$\{(x, y, z) : F(x, y, z) = c\}, \quad c \text{ constant.}$$

If $\frac{\partial F}{\partial z} \neq 0$ at some pt $\vec{r}_0 = (x_0, y_0, z_0)$ in this set, by the

implicit function theorem, there exists some function $f(x, y)$ for

$(x, y) \in$ some open set G s.t.

$$F(x, y, f(x, y)) = C,$$

that's, the level set of $F = C$ is described as $z = f(x, y)$ near the pt \vec{r}_0 . Similar situations hold when F_y or $F_z \neq 0$. Putting things together, it

$$\nabla F(\vec{r}_0) \neq (0, 0, 0),$$

then the level set $F = C$ is an explicit surface near \vec{r}_0 .

eg 1. the sphere.

$$F(x, y, z) = x^2 + y^2 + z^2.$$

$$\nabla F = z(x, y, z) \neq (0, 0, 0) \text{ if } (x, y, z) \neq (0, 0, 0).$$

So, the level sets of $F = C$ define implicit surfaces. In fact $F(x, y, z) = a^2$ ($a > 0$) is the sphere of radius a .

Explicit form can be obtained by specifying a pt on it.

Taking $\vec{r}_0 = (0, 0, 1)$,

$$f(x, y) = \sqrt{a^2 - x^2 - y^2}, \quad (x, y) \in D_1$$

describes the hemisphere (upper) containing $(0, 0, 1)$. For $(0, 0, -1)$, it is

$$-\sqrt{a^2 - x^2 - y^2}.$$

For $(1, 0, 0)$, it is

$$\sqrt{a^2 - y^2 - z^2},$$

$(y, z) \in D_1$.

Parametric description can be obtained using polar coordinates

$$(\theta, \varphi) \mapsto (\cos \theta \sin \varphi, \sin \theta \sin \varphi, \cos \varphi) = \vec{r}(\theta, \varphi)$$

$$\frac{\partial \vec{r}}{\partial \theta} = (-\sin \theta \sin \varphi, \cos \theta \sin \varphi, 0)$$

$$\frac{\partial \vec{r}}{\partial \varphi} = (\cos \theta \cos \varphi, \sin \theta \cos \varphi, -\sin \varphi)$$

When $-\sin \varphi \neq 0$, that is $\varphi \neq 0, \pi$, $\frac{\partial \vec{r}}{\partial \theta}$ and $\frac{\partial \vec{r}}{\partial \varphi}$ are linearly independent.

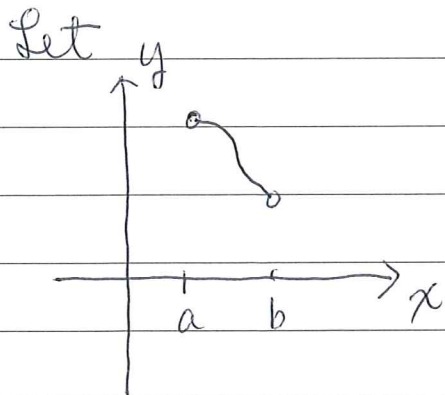
When $\varphi = 0$ or π , $\frac{\partial \vec{r}}{\partial \varphi} = (0, 0, 0)$, so no good. We conclude

that \vec{r} is a regular parametrization of the sphere on $[0, 2\pi] \times (0, \pi)$.

□

A class of surfaces commonly encountered are surface of revolution.

Let

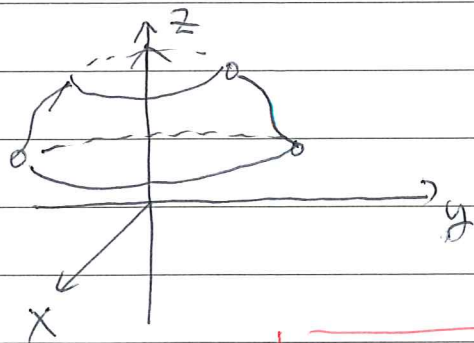


$(x(t), y(t))$ be a piece of curves in x - y plane.

Rotate it around the y -axis to get a surface. Change notations

$$y \mapsto z$$

$$x \mapsto r$$



The surface can be described by the parametrization

$$(d, t) \mapsto (r(t) \cos d, r(t) \sin d, z(t)), \quad d \in [0, 2\pi]$$

$$\frac{\partial \vec{r}}{\partial \alpha} = (-r \sin \alpha, r \cos \alpha, 0)$$

$$\frac{\partial \vec{r}}{\partial t} = (r' \cos \alpha, r' \sin \alpha, z')$$

when $z' \neq 0$, $\frac{\partial \vec{r}}{\partial \alpha}$ and $\frac{\partial \vec{r}}{\partial t}$ are l. indept. when $z' = 0$, but

$$r' \neq 0, \text{ then, as } \det \begin{vmatrix} -r \sin \alpha & r \cos \alpha \\ r' \cos \alpha & r' \sin \alpha \end{vmatrix} = -rr' \neq 0,$$

$\frac{\partial \vec{r}}{\partial \alpha}$ and $\frac{\partial \vec{r}}{\partial t}$ still indept. We conclude that as long as $(x(t), y(t))$

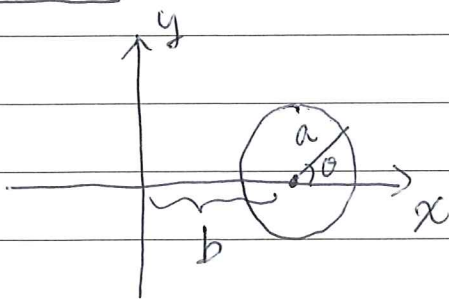
is regular curve, $\vec{r}(\alpha, t)$ is regular surface.

When a curve is given by explicit form $y = f(x)$ or implicit form $F(x, y) = c$, its corresponding surface of revolution are just

$$z = f(r), \quad r = (x^2 + y^2)^{1/2}, \quad \text{or}$$

$$F(r, z) = c.$$

e.g. 2 Torus



$$b > a > 0$$

the curve

$$(x(\theta), y(\theta)) = (b + a \cos \theta, a \sin \theta)$$

the torus

$$(\alpha, \theta) \mapsto ((b + a \cos \theta) \cos \alpha, (b + a \cos \theta) \sin \alpha, a \sin \theta)$$

$$\frac{\partial \vec{r}}{\partial \alpha} = (-(b+a \cos \theta) \sin \alpha, (b+a \cos \theta) \cos \alpha, 0)$$

$$\frac{\partial \vec{r}}{\partial \theta} = (-a \sin \theta \cos \alpha, -a \sin \theta \sin \alpha, a \cos \theta)$$

$$\frac{\partial \vec{r}}{\partial \alpha} \times \frac{\partial \vec{r}}{\partial \theta} = \left(a(b+a \cos \theta) \cos \theta \overset{\cos \alpha}{\uparrow}, (b+a \cos \theta) a \cos \theta \overset{\sin \alpha}{\uparrow}, a(b+a \cos \theta) \sin \theta \right)$$

$$\left| \frac{\partial \vec{r}}{\partial \alpha} \times \frac{\partial \vec{r}}{\partial \theta} \right| = a(b+a \cos \theta) > 0 \quad (\because b > a > 0)$$

So the torus is a regular surface.

the torus can be expressed as implicit form, starting with

$$(x-b)^2 + y^2 - a^2 = 0$$

$$\begin{array}{l} x \rightarrow r \\ y \rightarrow z \end{array} \quad (r-b)^2 + z^2 - a^2 = 0$$

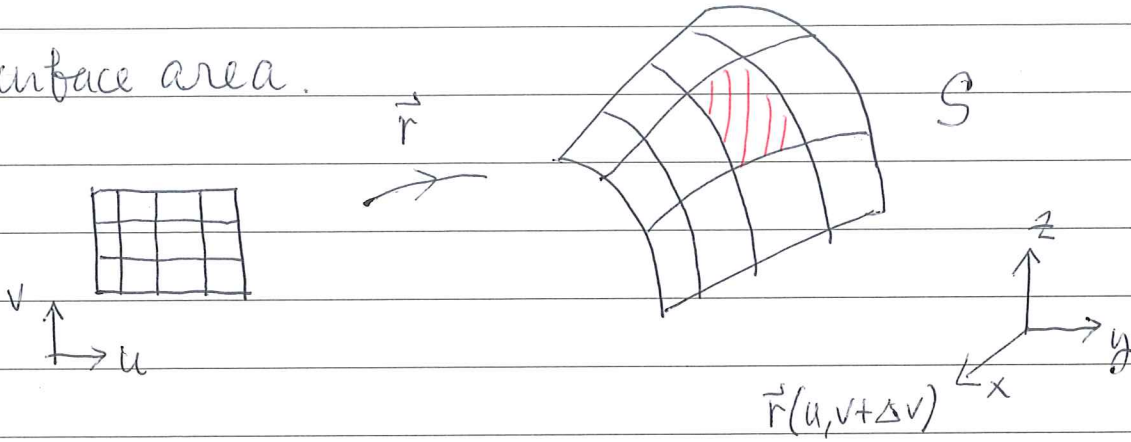
$$\sqrt{x^2 + y^2} = \sqrt{a^2 - z^2} + b$$

$$x^2 + y^2 = a^2 - z^2 + 2b\sqrt{a^2 - z^2} + b^2$$

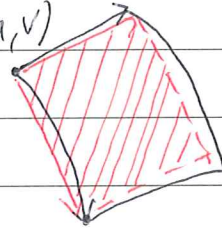
$\therefore (x^2 + y^2 + z^2 - a^2 - b^2)^2 = 4b(a^2 - z^2)$ is the implicit form of the torus.

Remark. The circle $x^2 + y^2 = b^2$ is a closed loop lying inside the torus which can't contract to a point inside the torus. So the solid \checkmark torus is not simply connected.

• Surface area.



A partition on $R = (u, v)$ -plane $\vec{r}(u, v)$ introduces a generalized partition on the surface S .



area of (red) parallelogram at $\vec{r}(u, v), \vec{r}(u+\Delta u, v), \vec{r}(u, v+\Delta v), \vec{r}(u+\Delta u, v+\Delta v)$

Consider a small portion vertices $\vec{r}(u, v), \vec{r}(u+\Delta u, v), \vec{r}(u, v+\Delta v), \vec{r}(u+\Delta u, v+\Delta v)$.

$$\approx \frac{\partial \vec{r}(u, v)}{\partial u} \Delta u \times \frac{\partial \vec{r}(u, v)}{\partial v} \Delta v$$

$$\begin{aligned} \vec{r}(u+\Delta u, v) &= \vec{r}(u, v) + \frac{\partial \vec{r}(u, v)}{\partial u} \Delta u + \dots \text{higher order terms} \\ &\sim \vec{r}(u, v) + \frac{\partial \vec{r}(u, v)}{\partial u} \Delta u \end{aligned}$$

$$\begin{aligned} \vec{r}(u, v+\Delta v) &= \vec{r}(u, v) + \frac{\partial \vec{r}(u, v)}{\partial v} \Delta v + \text{higher order terms} \\ &\sim \vec{r}(u, v) + \frac{\partial \vec{r}(u, v)}{\partial v} \Delta v \end{aligned}$$

So the area of this small portion is approximately

$$\begin{aligned} &\left| \frac{\partial \vec{r}(u, v)}{\partial u} \Delta u \times \frac{\partial \vec{r}(u, v)}{\partial v} \Delta v \right| \\ &= \left| \frac{\partial \vec{r}(u, v)}{\partial u} \times \frac{\partial \vec{r}(u, v)}{\partial v} \right| \Delta u \Delta v \end{aligned}$$

Summing up all this small portion and letting $\|P\| \rightarrow 0$, one get

$$\iint \left| \frac{\partial \vec{r}}{\partial u} \times \frac{\partial \vec{r}}{\partial v} \right| dA(u, v)$$



It justifies the following definition: Let $\vec{r}: \mathcal{D} \rightarrow S$ be a regular parametrization of the surface S . the area of S is defined to be surface

$$\text{Area of } S = \iint_{\mathcal{D}} |\vec{r}_u \times \vec{r}_v| dA(u, v).$$

e.g. 3 Find the surface area of the torus in e.g. 2.

We already have

$$|\vec{r}_\alpha \times \vec{r}_\theta| = a(b + a \cos \theta)$$

\therefore the area of the torus is

$$\begin{aligned} & \iint_R a(b + a \cos \theta) dA & R = [0, 2\pi] \times [0, 2\pi] \\ & = \int_0^{2\pi} \int_0^{2\pi} (ab + a^2 \cos \theta) d\theta d\alpha \\ & = 2\pi \int_0^{2\pi} (ab + a^2 \cos \theta) d\theta \\ & = 4\pi^2 ab. \quad \square \end{aligned}$$

When the surface is in explicit form $z = f(x, y)$.
The surface is given $(x, y, f(x, y))$

$$\frac{\partial \vec{r}}{\partial x} = (1, 0, f_x), \quad \frac{\partial \vec{r}}{\partial y} = (0, 1, f_y),$$

$$\frac{\partial \vec{r}}{\partial x} \times \frac{\partial \vec{r}}{\partial y} = -f_x \hat{i} - f_y \hat{j} + \hat{k}, \text{ so}$$

$$\begin{aligned} \left| \frac{\partial \vec{r}}{\partial x} \times \frac{\partial \vec{r}}{\partial y} \right| &= \sqrt{1 + f_x^2 + f_y^2} \\ &= \sqrt{1 + |\nabla f|^2} \end{aligned}$$

Thus, we have,

when S is given by $z = f(x, y)$ over $D \subset \mathbb{R}^2$. then the area is

$$\text{Area of } S = \iint_D \sqrt{1 + |\nabla f|^2} dA(x, y).$$

Finally, when S is given in ~~an~~ implicit form

$S = \{(x, y, z) : F(x, y, z) = c, \nabla F(x, y, z) \neq 0\}$. We have some $z = f(x, y)$ s.t

$$F(x, y, f(x, y)) = c.$$

It follows that $\frac{\partial F}{\partial x} + \frac{\partial F}{\partial z} f_x = 0$, $\frac{\partial F}{\partial y} + \frac{\partial F}{\partial z} f_y = 0$, so

$$f_x = \frac{-F_x}{F_z}, \quad f_y = \frac{-F_y}{F_z}$$

$$\sqrt{1 + f_x^2 + f_y^2} = \frac{|\nabla F|}{|F_z|}.$$

We conclude, when S is given implicitly by $F(x, y, z) = c$

and it defines $z=f(x,y)$ over some D , then

$$\text{area of } S = \iint_D \frac{|\nabla F|}{|F_z|} dA(x,y)$$

eg. 4 Find the surface area of the paraboloid $z=x^2+y^2$ bounded by $z=4$.

$$f(x,y) = x^2 + y^2$$

$$f_x = 2x, f_y = 2y \quad \therefore \sqrt{1 + f_x^2 + f_y^2} = \sqrt{1 + 4(x^2 + y^2)}$$

The surface is the paraboloid over D_2 .

$$\begin{aligned} \therefore \text{Area} &= \iint_{D_2} \sqrt{1 + 4(x^2 + y^2)} dA(x,y) \\ &= \int_0^{2\pi} \int_0^2 \sqrt{1 + 4r^2} r dr d\theta \\ &= \frac{2\pi}{2} \int_0^4 \sqrt{1 + 4t} dt \\ &= \frac{\pi}{6} [(\sqrt{17})^3 - 1] \end{aligned}$$

• Surface Integral of a Function

Let G be a fun on the surface S . Its integral is